History of Starting with Signal Processing (SP) First

Classically (e.g. 1950s to 1990s), Electrical Engineering started with circuits Signal processing through circuits (historical start)

In the 1990s, Digital SP: 4th year or Grad course

Why not start with Signal Processing?

Signal Processing first, then circuits enabled through SP



Ron Schafer



Jim McClellan

And others at GT, those who founded DSP and some good friends at Rice, Rose-Hulman Fall 1999 at GT: Full implementation Requirement for all ECE students



SP First (GT 1999)

• Two large lecture sessions

Each week:

- Faculty Led Recitation Session
- Weekly computer (MATLAB) exercises



Complex Addition: (rectangular)

$$C_1 + C_2 = (a_1 + jb_1) + (a_2 + jb_2) = a_1 + a_2 + j(b_1 + b_2)$$

Complex Multiplication: (polar)

$$C_1 C_2 = R_1 e^{j\theta_1} R_2 e^{j\theta_2} = R_1 R_2 e^{j(\theta_1 + \theta_2)}$$

One often converts between rectangular and polar forms

Euler's Formula:

$$\frac{e^{j\theta} = \cos\theta + j\sin\theta}{e^{j\theta} = e^{j2\pi} = -e^{j\pi} = 1}$$

$$e^{j\pi/2} = -e^{j3\pi/2} = j$$

$$e^{j\theta} + e^{-j\theta} = 2\cos\theta \to \cos\theta = \frac{e^{j\theta} + e^{-j\theta}}{2}$$

$$e^{j\theta} - e^{-j\theta} = 2j\sin\theta \to \sin\theta = \frac{e^{j\theta} - e^{-j\theta}}{2j}$$

$$\cos^{2}(\theta) = \left(\frac{e^{j\theta} + e^{-j\theta}}{2}\right)^{2} \qquad \sin^{2}(\theta) = \left(\frac{e^{j\theta} - e^{-j\theta}}{2j}\right)^{2} \qquad \cos(\theta)\sin(\theta) = \left(\frac{e^{j\theta} + e^{-j\theta}}{2}\right) \left(\frac{e^{j\theta} - e^{-j\theta}}{2j}\right)$$
$$= \frac{e^{j2\theta} + 2 + e^{-j2\theta}}{4} \qquad = \frac{-e^{j2\theta} + 2 - e^{-j2\theta}}{4} \qquad = \frac{-e^{j2\theta} - e^{-j2\theta}}{4j}$$
$$= \frac{1 + \cos(2\theta)}{2} \qquad = \frac{1 - \cos(2\theta)}{2} \qquad = -\sin(2\theta)/2$$

$$\cos^{3}(\theta) = \left(\frac{e^{j\theta} + e^{-j\theta}}{2}\right)^{3}$$
$$= \frac{1}{8} \left(e^{j3\theta} + 3e^{j\theta} + 3e^{-j\theta} + e^{-j3\theta}\right)$$
$$= \frac{1}{8} \left(e^{j3\theta} + e^{-j3\theta} + 3e^{j\theta} + 3e^{-j\theta}\right)$$
$$= \frac{3}{4} \cos(\theta) + \frac{1}{4} \cos(3\theta)$$

$$\sin^{3}(\theta) = \left(\frac{e^{j\theta} - e^{-j\theta}}{2j}\right)^{3}$$
$$= \frac{1}{8j} \left(e^{j3\theta} - e^{-j3\theta} - 3e^{j\theta} + 3e^{-j\theta}\right)$$
$$= \frac{1}{8j} \left(e^{j3\theta} - 3e^{j\theta} + 3e^{-j\theta} - e^{-j3\theta}\right)$$
$$= \frac{1}{4} \sin(3\theta) - \frac{3}{4} \sin(\theta)$$

Sinusoidal functions

$$\begin{split} y_{1}(t) &= A_{1} \cos(2\pi ft + \theta_{1}) \to A_{1}e^{j(2\pi ft + \theta_{1})} \\ & (\text{Amplitude}) & (\text{phase}) \\ f &= \text{frequency of the sinusoid (Hz)} \\ & T &= 1/f = \text{period of the sinusoid (s)} \\ & 2\pi \text{ f} = \text{radians of the sinusoid (rad)} \\ Re\left\{A_{1}e^{j(2\pi ft + \theta_{1})}\right\} &= Re\left\{A_{1}\cos(2\pi ft + \theta_{1}) + j\sin(2\pi ft + \theta_{1})\right\} \\ &= A_{1}\cos(2\pi ft + \theta_{1}) \\ y_{2}(t) &= A_{2}\cos(2\pi ft + \theta_{2}) \to A_{2}e^{j(2\pi ft + \theta_{2})} \\ \text{Summation } (y_{1}(t) + y_{2}(t)): \\ & (\text{Same frequency}) & \boxed{Re\left\{\sum_{k=1}^{n} X_{k}\right\} = \sum_{k=1}^{n} Re\left\{X_{k}\right\}} \\ y_{1}(t) + y_{2}(t) &= A_{1}\cos(2\pi ft + \theta_{1}) + A_{2}\cos(2\pi ft + \theta_{2}) \\ &= Re\left\{A_{1}e^{j(2\pi ft + \theta_{1})} + A_{2}e^{j(2\pi ft + \theta_{2})}\right\} \\ &= Re\left\{A_{1}e^{j(2\pi ft + \theta_{1})} + A_{2}e^{j(2\pi ft + \theta_{2})}\right\} \\ &= Re\left\{A_{1}e^{j(2\pi ft + \theta_{1})} + A_{2}e^{j(2\pi ft + \theta_{2})}\right\} \\ &= Re\left\{A_{1}e^{j\theta_{1}} + A_{2}e^{j\theta_{2}}\right\} \\ &= Re\left\{(5e^{j\pi/3} + 5e^{j2\pi/3})e^{j200t}\right\} \\ &= Re\left\{(5\sqrt{3}e^{j\pi/2})e^{j200t}\right\} \\ &= Re\left\{(5\sqrt{3}e^{j\pi/2})e^{j200t}\right\} \\ &= 5\sqrt{3}\cos(200t + \pi/2) \end{aligned}$$

Linear Functions: f(x)

$$f(ax + by) = af(x) + bg(y)$$

$$f(ag(x) + bh(y)) = af(g(x)) + bf(g(y))$$

Example functions

DifferentiationIntegration $\frac{d}{dt}(ag(x) + bh(y)) =$ $\int (ag(x) + bh(y)) dt =$ $a\frac{d}{dt}g(x) + b\frac{d}{dt}h(y)$ $a\int g(x)dt + b\int h(y)dt$

Linear gain factor: $f(ax) = af(x) \rightarrow \frac{d}{dt}(ag(x)) = a\frac{d}{dt}g(x), \int (ag(x)) dt = a \int g(x) dt$

Linear (Time-Independent) Systems are characterized by sinusoids and exponentials

Single frequency input \rightarrow Single frequency ouput

$$\sin(\omega t) \rightarrow \begin{array}{c} \text{Linear} \\ \text{System} \end{array} \rightarrow H \sin(\omega t + \theta)$$